

Elastic Collisions

* In every collision (neglecting friction), momentum is conserved due to Newton's Third Law:

If the objects experience equal but opposite forces during a collision, they also experience equal but opposite impulses which means they have equal but opposite changes in momenta (ie one object's loss is the other's gain)

* Kinetic energy may or may not be conserved in a collision. If it is conserved \Rightarrow ELASTIC COLLISION

To see if a collision is elastic, you must know all the velocities \Rightarrow use conservation of momentum to find a missing velocity.

<u>MP 320</u>		<u>BEFORE</u>		<u>AFTER</u>	
M	B	S	B	S	
m	0.250 kg	0.800 kg	0.250 kg	0.800 kg	
V	+ 5.00 m/s	0	- 2.62 m/s	V	
(mv)	$1.25 \text{ kg}\cdot\text{m/s}$	0	$-0.655 \frac{\text{kg}\cdot\text{m/s}}{\text{kg}\cdot\text{m/s}}$	$(0.800 \text{ kg})V$	

$\xrightarrow{\text{P}_{\text{total}}}$ + the original direction of the bill. ball.

- Opp. the original direction of the bill. ball

$$\begin{aligned} \vec{P}_{\text{total}} &= \vec{P}'_{\text{total}} \\ \vec{P}_B + \vec{P}_S &= \vec{P}'_B + \vec{P}'_S \\ + 1.25 \text{ kg}\cdot\text{m/s} + 0 &= -0.655 \text{ kg}\cdot\text{m/s} + (0.800 \text{ kg})V \\ 1.905 \text{ kg}\cdot\text{m/s} &= (0.800 \text{ kg})V \end{aligned}$$

$$V = +2.38 \text{ m/s}$$

To see if ELASTIC:

$$\vec{V} = 2.38 \text{ m/s} \quad [\text{in the original direction of the billiard}]$$

BEFORE:

$$\text{Bill Ball: } E_k = \frac{1}{2}mv^2 = \frac{1}{2}(0.250 \text{ kg})(5.00 \text{ m/s})^2 = 3.125 \text{ J}$$

$$\text{Steel Ball: } E_k = 0$$



AFTER

$$\text{Bill Ball: } E_k = \frac{1}{2}mv^2 = \frac{1}{2}(0.250 \text{ kg})(2.62 \text{ m/s})^2 = 0.85805 \text{ J}$$

$$\text{Steel Ball: } E_k = \frac{1}{2}(0.800 \text{ kg})(2.38 \text{ m/s})^2 = 2.26576 \text{ J}$$



Since $E_{k+\text{total}} = E'_{k+\text{total}}$, the collision is:

ELASTIC

To Do

① PP | 322

② Review: p 277 | 23-39 (Chapt 6)

p 328 | 20-23 (Chapt 7)

TEST - Thurs, Dec 9th

Chapter 6 - Work, Energy + Power

- $W = F_d \Delta d$
- $W = \bar{F} d \cos \theta$
- $W = \text{area under a } F\text{-d graph}$
- When no work is done
- Kinetic energy: $E_k = \frac{1}{2}mv^2$
- Gravitational Potential Energy: $E_g = mgh$
- Elastic Potential Energy: $E_p = \frac{1}{2}kx^2$ (Hooke's Law)
 $F_a = kx$
- Work-Energy Theorem: $W = \Delta E$
- Power: $P = \frac{W}{\Delta t}$
- Efficiency = $\frac{E_o}{E_i} \times 100\%$

Chapter 7 - Conservation of Energy + Momentum

- Law of Conservation of Mechanical Energy:

Single object
or cart/spring system

$$E_{\text{total}}' = E_{\text{total}}$$

$$E_g + E_k + E_p = E_g' + E_k' + E_p'$$

BEFORE = AFTER

(neglecting friction/air res)

- Law of Conservation of Momentum

2 objects

$$\vec{P}_{\text{total}} = \vec{P}'_{\text{total}}$$

$$\vec{P}_A + \vec{P}_B = \vec{P}'_A + \vec{P}'_B$$

(BEFORE) (AFTER)

(in an isolated system)

- * use mvp chart to organize info
- * momentum is a vector (dir is impl.)